

Presentation at Research Group

DALE: Differential Accumulated Local Effects for efficient and accurate global explanations

Vasilis Gkolemis^{!,*}

[!]ATHENA Research and Innovation Center

^{*}Harokopio University of Athens

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Who we are

- **Vasilis Gkolemis:**
 - ▶ Research Assistant at ATHENA Research Center ([ATHENA RC](#))
 - ▶ First-year PhD at Harokopio University of Athens ([HUA](#))
 - ▶ Main focus: Explainability under uncertainty
- Supervisors:
 - ▶ [Christos Diou](#) (HUA) → Generalization, Few(Zero)-shot learning
 - ▶ [Eirini Ntoutsi](#) (UniBw-M) → Explainability, Fairness
 - ▶ [Theodore Dalamagas](#) (ATHENA) → Databases, data semantics
- Paper I will present
 - ▶ [DALE: Differential Accumulated Local Effects for efficient and accurate global explanations](#)
 - ▶ Accepted at [Asian Conference Machine Learning \(ACML\) 2022](#)

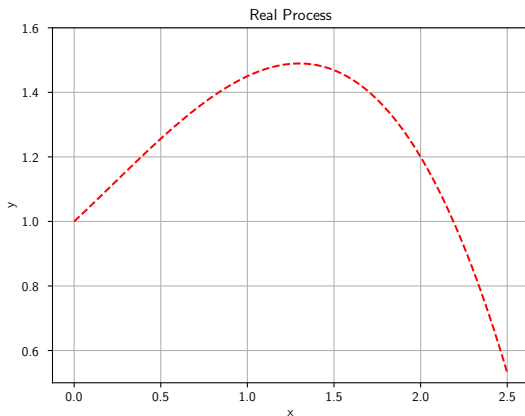
Questions

- Why did the model make a specific decision? **local XAI**
- What could we change so that the model will make a different decision? **counterfactual**
- Can we summarize the model's behavior? **global XAI**
- If models are knowledge extractors, what have they learned? **global XAI**

Feature Effect: global, model-agnostic, outputs a $1D$ plot

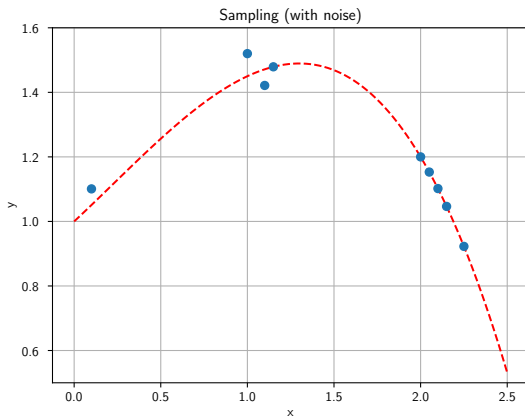
Example

Consider the following mapping $x \rightarrow y$



Example

Process unknown \rightarrow we only have samples



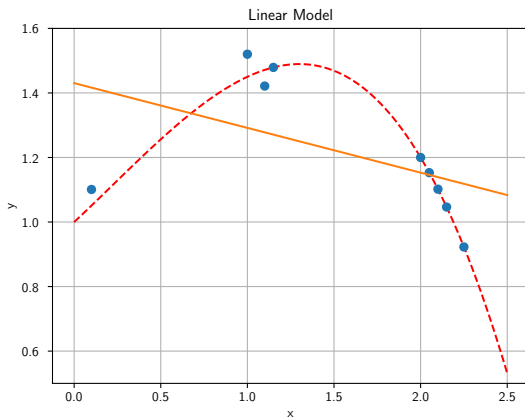
Example

Our goal is to model the process using the available samples (regression)

Example

Linear model \rightarrow Underfitting!

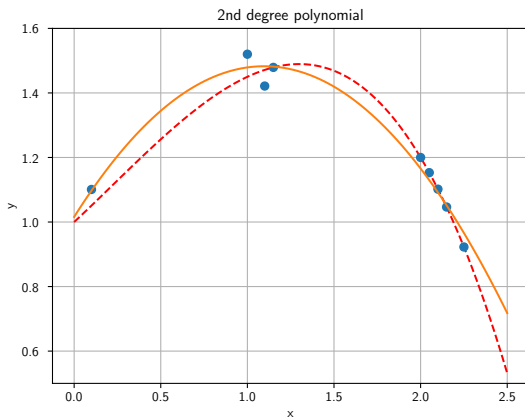
$$y = w_1 \cdot x + w_0$$



Example

2nd degree polynomial → Decent Fit!

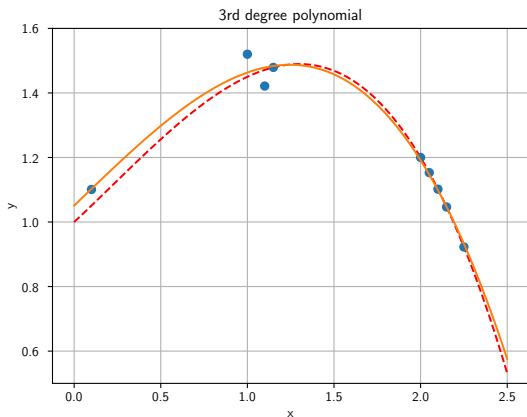
$$y = w_2 \cdot x^2 + w_1 \cdot x + w_0$$



Example

3rd degree polynomial → Good Fit!

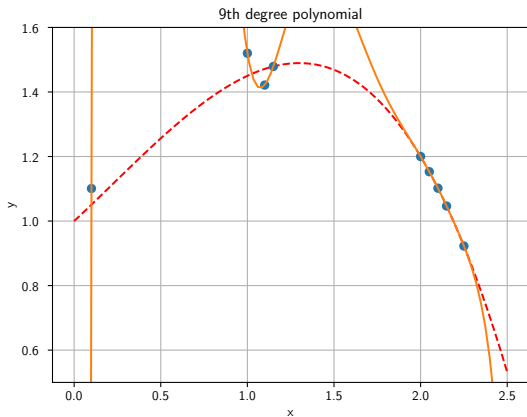
$$y = w_3 \cdot x^3 + w_2 \cdot x^2 + w_1 \cdot x + w_0$$



Example

9th degree polynomial → Overfitting!

$$y = \sum_{i=0}^9 w_i \cdot x^i$$



Problem diagnosis

- Model behavior is **explained** by the shape of the function
- Overfitting, Underfitting are easily diagnosed
- If the input has multiple dimensions D ?
 - ▶ We often have tens or hundreds of features
 - ▶ Images and signals: Several thousands of input dimensions
- Example: [Risk Factors for Cervical Cancer Dataset](#)
 - ▶ input: 15 features (smoker, years of hormonal contraceptives, age)
 - ▶ output: predict whether a woman will get cervical cancer

Feature Effect

$y = f(x_s) \rightarrow$ plot showing the effect of x_s on the output y

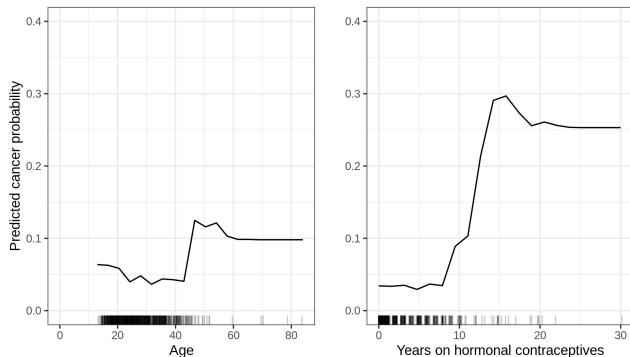


Figure: Image taken from Interpretable ML book (Molnar, 2022)

Feature Effect is simple and intuitive.

Feature Effect Methods

- $x_s \rightarrow$ feature of interest, $\mathbf{x}_c \rightarrow$ other features
- Isolating the effect of x_s is a difficult task:
 - ▶ features are correlated
 - ▶ f has learned complex interactions
- Three well-known methods:
 - ▶ Partial Dependence Plots (PDP)
 - ▶ M-Plots
 - ▶ Accumulated Local Effects (ALE)

Partial Dependence Plots (PDP)

- Proposed by J. Friedman on 2001¹ and is the marginal **effect** of a feature to the model output:

$$f_s(x_s) = \mathbb{E}_{\mathbf{x}_c} [f(x_s, \mathbf{x}_c)] = \int f(x_s, \mathbf{x}_c) p(\mathbf{x}_c) d\mathbf{x}_c$$

where:

- x_s is the feature whose effect we wish to compute
 - \mathbf{x}_c are the rest of the features
- Approximation:

$$\hat{f}_s(x_s) = \frac{1}{n} \sum_{i=1}^n f(x_s, \mathbf{x}_c^{(i)})$$

¹J. Friedman. "Greedy function approximation: A gradient boosting machine." Annals of statistics (2001): 1189-1232

Issues with PDPs

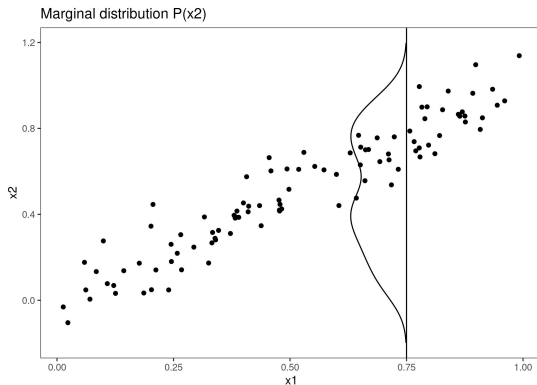


Figure: C. Molnar, IML book

- Correlated features

- ▶ To compute the effect of $x_{\text{age}} = 20$ on the output (cancer probability) it will integrate over all $x_{\text{years_contraceptives}}$ values, e.g., $[0, 50]$
- ▶ f can have weird behavior when $x_{\text{age}} = 20, x_{\text{years_contraceptives}} = 20$ (out of distribution)
- ▶ As a result, we have a wrong estimation of the feature effect

- We use the value of x_s as a condition, so we integrate over $\mathbf{x}_c | x_s$

$$f(x_s) = \mathbb{E}_{\mathbf{x}_c | x_s} [f(x_s, \mathbf{x}_c)] = \int f(x_s, \mathbf{x}_c) p(\mathbf{x}_c | x_s) d\mathbf{x}_c$$

where:

- ▶ x_s is the feature whose effect we wish to compute
 - ▶ \mathbf{x}_c the rest of the features
- Approximation:

$$f_s(x_s) = \frac{1}{n} \sum_{i: x_s^{(i)} \approx x_s} f(x_s, \mathbf{x}_c^{(i)})$$

In the previous example

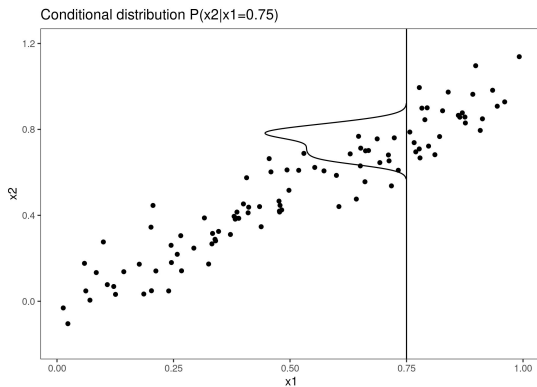


Figure: C. Molnar, IML book

Issues with M-Plots

- Aggregated effect symptom \rightarrow the calculated effects result from the combination of all (correlated) features
- Real effect:
 - ▶ $x_{\text{age}} = 50 \rightarrow 10$
 - ▶ $x_{\text{years_contraceptives}} = 20 \rightarrow 10$
 - ▶ aggregated effect close to 20
- Because $x_{\text{age}}, x_{\text{years_contraceptives}}$ are correlated, MPlot may assign:
 - ▶ $x_{\text{age}} = 50 \rightarrow 17 \approx$ aggregated effect
 - ▶ $x_{\text{years_contraceptives}} = 20 \rightarrow 17 \approx$ aggregated effect

Accumulated Local Effects (ALE)²

- Resolves problems that result from the feature correlation by computing differences over a (small) window

$$f(x_s) = \int_{x_{min}}^{x_s} \mathbb{E}_{\underbrace{\mathbf{x}_c | z}_{realistic}} \left[\underbrace{\frac{\partial f}{\partial x_s}(z, \mathbf{x}_c)}_{isolates} \right] \partial z$$

²D. Apley and J. Zhu. “Visualizing the effects of predictor variables in black box supervised learning models.” *Journal of the Royal Statistical Society: Series B (Statistical Methodology)* 82.4 (2020): 1059-1086.

ALE approximation

ALE definition: $f(x_s) = \int_{x_{s,min}}^{x_s} \mathbb{E}_{\mathbf{x}_c|z} \left[\frac{\partial f}{\partial x_s}(z, \mathbf{x}_c) \right] dz$

ALE approximation: $f(x_s) = \underbrace{\sum_k^{k_x} \frac{1}{|S_k|}}_{\text{bin effect}} \underbrace{\sum_{i:\mathbf{x}^i \in S_k} [f(z_k, \mathbf{x}_c^i) - f(z_{k-1}, \mathbf{x}_c^i)]}_{\text{point effect}}$

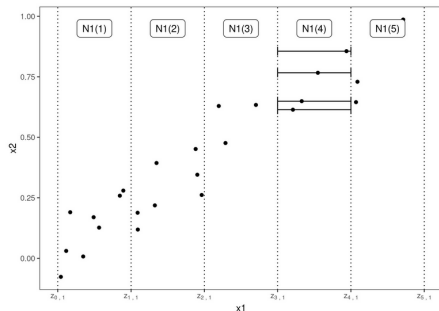


Figure: Image taken from Interpretable ML book (Molnar, 2022)

ALE approximation - weaknesses

$$f(x_s) = \sum_k^{k_x} \frac{1}{|S_k|} \sum_{i: x^i \in S_k} \underbrace{[f(z_k, x_c^i) - f(z_{k-1}, x_c^i)]}_{\text{point effect}} \underbrace{\hspace{10em}}_{\text{bin effect}}$$

- Point Effect \Rightarrow evaluation **at bin limits**
 - ▶ 2 evaluations of f per point \rightarrow slow
 - ▶ change bin limits, pay again $2 * N$ evaluations of f \rightarrow restrictive
 - ▶ broad bins may create out of distribution (OOD) samples \rightarrow not-robust in wide bins

ALE approximation has some weaknesses

Recap!

- PDP → problems with correlated features → Unrealistic instances
- MPlot → problems with correlated features → Aggregated effects
- ALE → resolves both issues! But:
- ALE approximation (estimation of ALE from the training set)
 - ▶ slow when there are many features
 - ▶ unrealistic instances when bins become bigger
- Differential ALE (DALE)!

Our proposal: Differential ALE

$$f(x_s) = \Delta x \underbrace{\sum_k \frac{1}{|S_k|} \sum_{i: x^i \in S_k} \underbrace{\left[\frac{\partial f}{\partial x_s}(x_s^i, \mathbf{x}_c^i) \right]}_{\text{point effect}}}_{\text{bin effect}}$$

- Point Effect \Rightarrow evaluation **on instances**
 - ▶ Fast \rightarrow use of auto-differentiation, all derivatives in a single pass
 - ▶ Versatile \rightarrow point effects computed once, change bins without cost
 - ▶ Secure \rightarrow does not create artificial instances

For **differentiable** models, DALE resolves ALE weaknesses

DALE is faster and versatile - theory

$$f(x_s) = \Delta x \underbrace{\sum_k \frac{1}{|S_k|} \sum_{i: x^i \in S_k} \underbrace{\left[\frac{\partial f}{\partial x_s}(x_s^i, \mathbf{x}_c^i) \right]}_{\text{point effect}}}_{\text{bin effect}}$$

- Faster
 - ▶ gradients wrt all features $\nabla_{\mathbf{x}} f(\mathbf{x}^i)$ in a single pass
 - ▶ auto-differentiation must be available (deep learning)
- Versatile
 - ▶ Change bin limits, with near zero computational cost

DALE is faster and allows redefining bin-limits

DALE is faster and versatile - Experiments

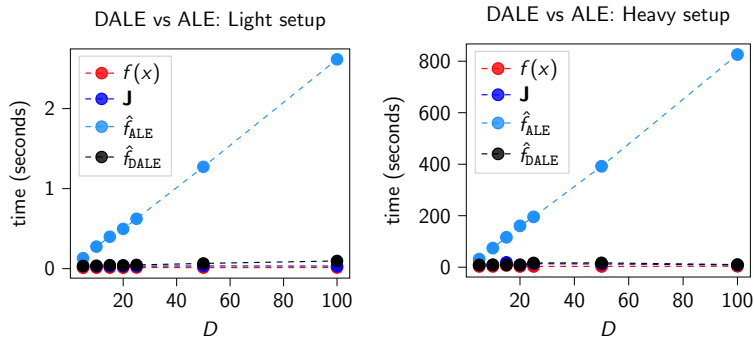


Figure: Light setup; small dataset ($N = 10^2$ instances), light f . Heavy setup; big dataset ($N = 10^5$ instances), heavy f

DALE considerably accelerates the estimation

DALE uses on-distribution samples - Theory

$$f(x_s) = \underbrace{\sum_k \frac{1}{|\mathcal{S}_k|}}_{\text{bin effect}} \sum_{i: \mathbf{x}^i \in \mathcal{S}_k} \underbrace{\left[\frac{\partial f}{\partial x_s}(\mathbf{x}_s^i, \mathbf{x}_c^i) \right]}_{\text{point effect}}$$

- point effect **independent** of bin limits
 - ▶ $\frac{\partial f}{\partial x_s}(\mathbf{x}_s^i, \mathbf{x}_c^i)$ computed on real instances $\mathbf{x}^i = (\mathbf{x}_s^i, \mathbf{x}_c^i)$
- bin limits affect only the **resolution** of the plot
 - ▶ wide bins \rightarrow low resolution plot, bin estimation from more points
 - ▶ narrow bins \rightarrow high resolution plot, bin estimation from less points

DALE enables wide bins without creating out of distribution instances

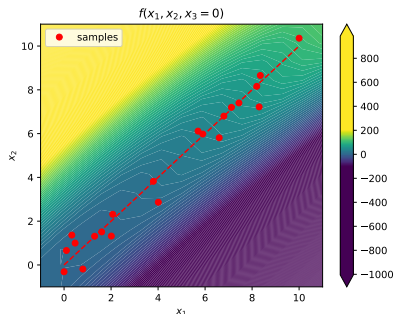
DALE uses on-distribution samples - Experiments

$$f(x_1, x_2, x_3) = x_1x_2 + x_1x_3 \pm g(x)$$

$$x_1 \in [0, 10], x_2 \sim x_1 + \epsilon, x_3 \sim \mathcal{N}(0, \sigma^2)$$

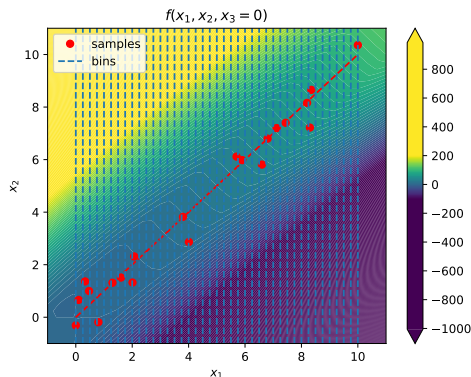
$$f_{\text{ALE}}(x_1) = \frac{x_1^2}{2}$$

- point effects affected by (x_1x_3)
(σ is large)
- bin estimation is noisy (samples are few)



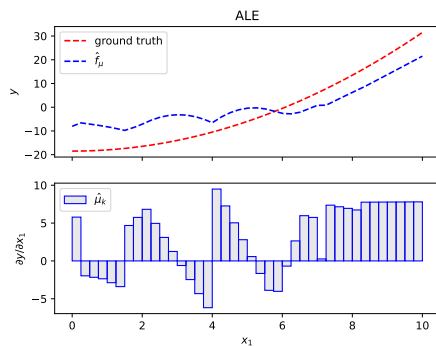
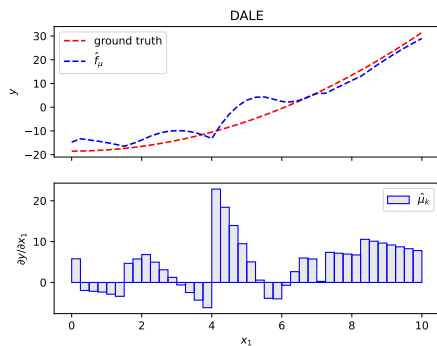
Intuition: we need wider bins (more samples per bin)

DALE vs ALE - 40 Bins



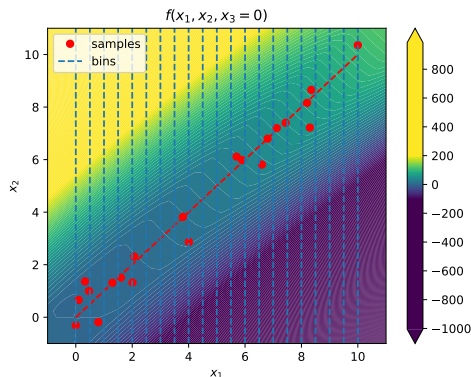
- DALE: on-distribution, noisy bin effect → poor estimation
- ALE: on-distribution, noisy bin effect → poor estimation

DALE vs ALE - 40 Bins



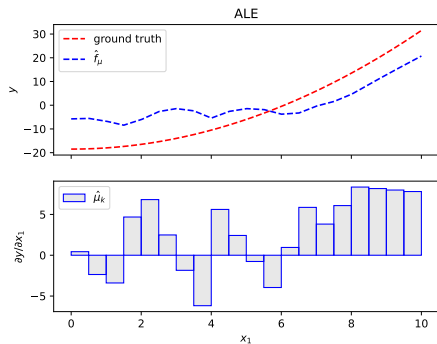
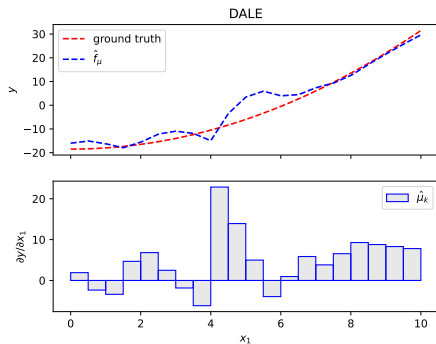
- DALE: on-distribution, noisy bin effect → **poor estimation**
- ALE: on-distribution, noisy bin effect → **poor estimation**

DALE vs ALE - 20 Bins



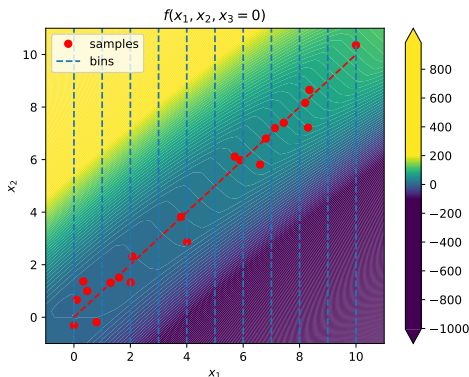
- DALE: on-distribution, noisy bin effect → poor estimation
- ALE: on-distribution, noisy bin effect → poor estimation

DALE vs ALE - 20 Bins



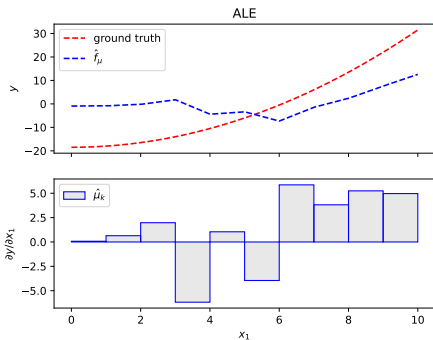
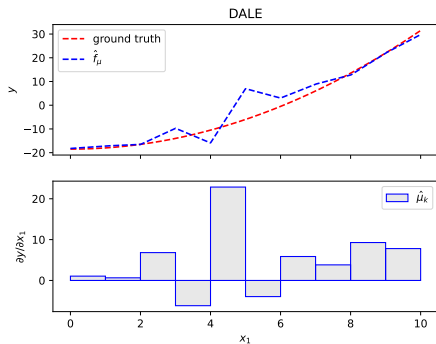
- DALE: on-distribution, noisy bin effect → **poor estimation**
- ALE: on-distribution, noisy bin effect → **poor estimation**

DALE vs ALE - 10 Bins



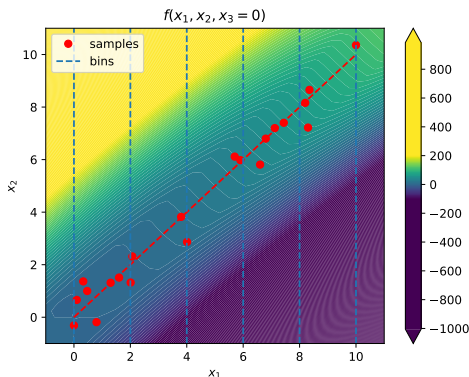
- DALE: on-distribution, noisy bin effect → poor estimation
- ALE: starts being OOD, noisy bin effect → poor estimation

DALE vs ALE - 10 Bins



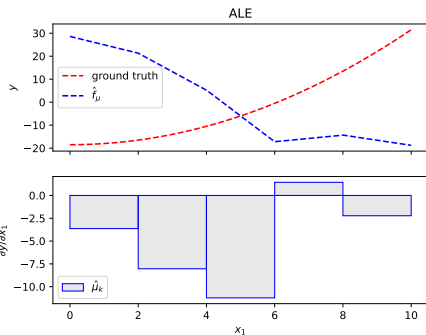
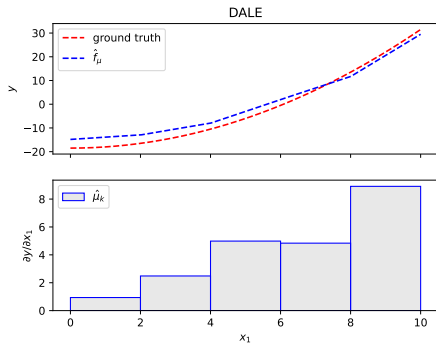
- DALE: on-distribution, noisy bin effect → poor estimation
- ALE: starts being OOD, noisy bin effect → poor estimation

DALE vs ALE - 5 Bins



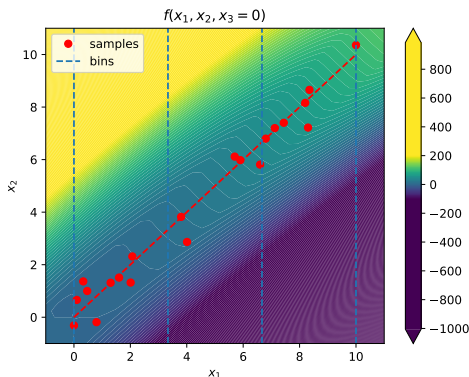
- DALE: on-distribution, robust bin effect → good estimation
- ALE: completely OOD, robust bin effect → poor estimation

DALE vs ALE - 5 Bins



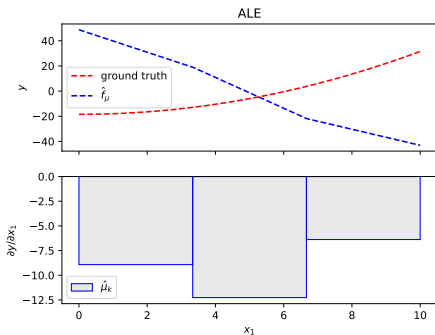
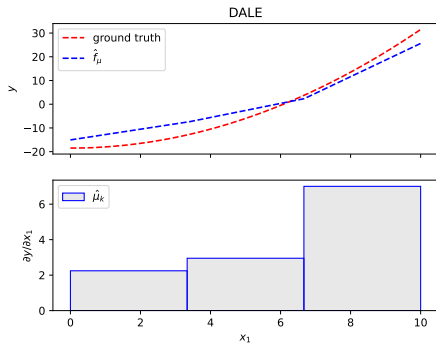
- DALE: on-distribution, robust bin effect → good estimation
- ALE: completely OOD, robust bin effect → poor estimation

DALE vs ALE - 3 Bins



- DALE: on-distribution, robust bin effect → good estimation
- ALE: completely OOD, robust bin effect → poor estimation

DALE vs ALE - 3 Bins



- DALE: on-distribution, robust bin effect → good estimation
- ALE: completely OOD, robust bin effect → poor estimation

Future Ideas (1)

PDPs use ICE plots, for exhibiting heterogeneity

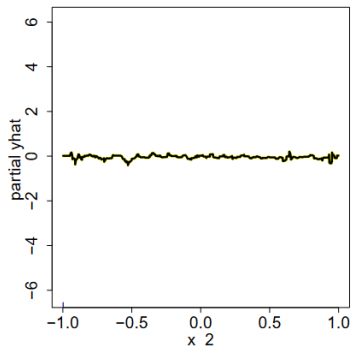


Figure: PDP plot, taken from [Goldstein et. al](#)

Interpretation? Maybe $y \perp\!\!\!\perp x_2$

Future Ideas (2)

PDPs use ICE plots, for exhibiting heterogeneity

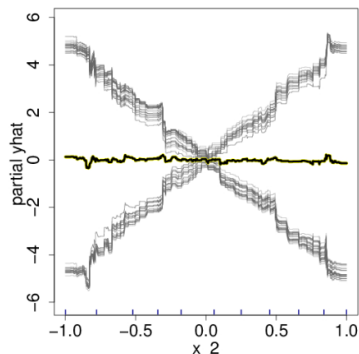


Figure: PDP-ICE plot, taken from [Goldstein et. al](#)

Interpretation now? Maybe $y \approx \pm 6x_2$ depending on a condition

Future Ideas (3)

- Could ALE plots do the same?
- Variance inside each bin?

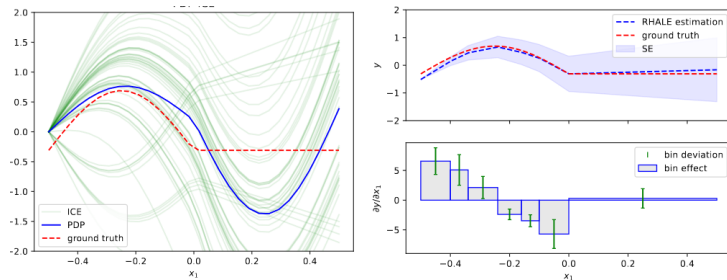


Figure: (Left) PDP-ICE (Right) ALE with heterogeneity

Future Ideas (4) - Regional Effect plots

- Heterogeneity → subspaces with homogeneous effects

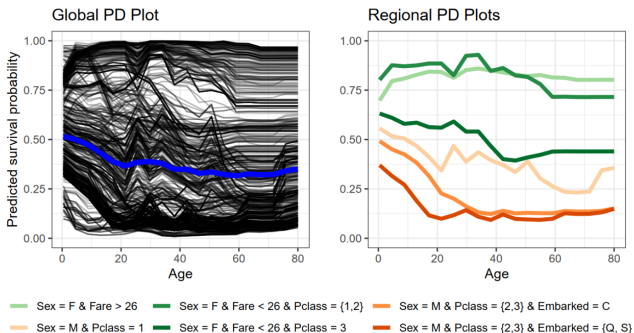




Figure: REPID: Regional Effect plots, taken from [Herbinger et. al](#)

Same idea on ALE?

Thank you

- Questions?

References I

-  Fanaee-T, Hadi and Joao Gama (2013). “Event labeling combining ensemble detectors and background knowledge”. In: *Progress in Artificial Intelligence*, pp. 1–15. ISSN: 2192-6352. DOI: [10.1007/s13748-013-0040-3](https://doi.org/10.1007/s13748-013-0040-3). URL: [\[WebLink\]](#).
-  Molnar, Christoph (2022). *Interpretable Machine Learning. A Guide for Making Black Box Models Explainable*. 2nd ed. URL: <https://christophm.github.io/interpretable-ml-book>.